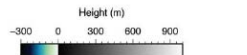


# Application of AUV technology for the mapping of polar shelf seas

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Howe et al., 2003,  
Maclachlan et al., 2010

Lockwood, In Prep  
Insh, In Prep  
W. Svalbard, Fram Strait

## Mapping mid-high latitude regions of glacially-influenced shelf



Western Scotland  
W. Svalbard  
Antarctica

NERC RATE  
Lo-Rise (Long-  
Range Transport  
of Radionuclides  
in the Marine  
Environment

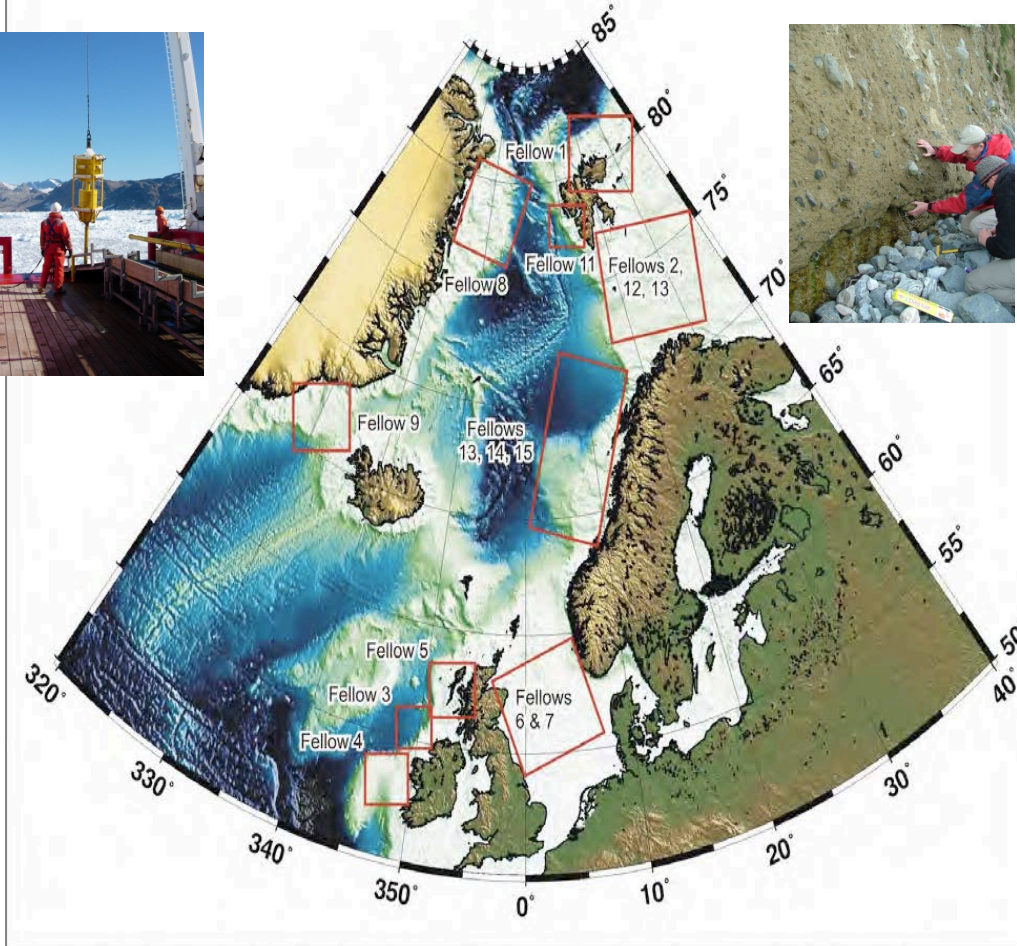
Vessel-based and recently  
AUV

Geomorphology, habitat  
Sediment dynamics



**MAREMAP**  
Marine Environmental  
Mapping Programme

Dove et al., 2015; Howe et al., 2015



**The overarching scientific goal of the GLANAM network :**

- 1. To determine the role of different glacial/non-glacial sedimentary processes in shaping the glaciated North Atlantic margins.**
- 2. To contribute to the understanding of the extent, timing and rates of decay of marine-based ice sheets.**
- 3. To contribute to the understanding of the influence the ice ages have imposed on the hydrocarbon systems on the glaciated North Atlantic margin**
- 4. To determine the influence of climate change and sedimentary processes on the fluid flow (and gas hydrate) systems on the glaciated North Atlantic margin.**
- 5. To identify the controlling factors and the role of submarine mass movements (with resulting tsunamis) on the glaciated North Atlantic margin.**



Klein 3000 dual frequency 100 kHz & 455 kHz (1000m depth)

Shallow water surveys uses a 30m flexible or 600m co-axial umbilical.

Navigation from Furuno or Garmin GPS

Side-scan sonar (2007)



Mohave ROV (2014)

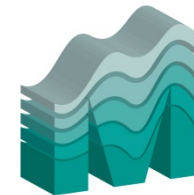
Wynn, R.B., Bett, B.J., Evans, A.J., Griffiths, G., Huvenne, V.A.I., Jones, A.R., Palmer, M.R., Dove, D., Howe, J.A., Boyd, T.J. and MAREMAP partners (2012) *Investigating the feasibility of utilizing AUV and Glider technology for mapping and monitoring of the UK MPA network*. Final report for Defra project MB0118. National Oceanography Centre, Southampton. 244 pp.

Gavia Offshore Surveyor (2015)



### AUV Freya configuration

- Offshore Surveyor base vehicle (500m depth rating)
- High-precision DVL aided Inertial Navigation System
- Swath Bathymetry 500kHz GeoSwath+
- Colour Camera
- Sound Velocity Meter , Obstacle Avoidance Sonar,



**MAREMAP**  
Marine Environmental  
Mapping Programme

**Scot - MRF**  
The Scottish Marine Robotics Facility





AUV Freya

80kg

2.7m long

9 boxes for transport

4hr endurance

~10-15 km<sup>2</sup> area per mission





**Thank you !**

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